## Washtenaw Community College Comprehensive Report

## **ROB 101 Robotics I - I** Effective Term: Fall 2022

### **Course Cover**

College: Advanced Technologies and Public Service Careers Division: Advanced Technologies and Public Service Careers Department: Advanced Manufacturing **Discipline:** Robotics **Course Number: 101** Org Number: 14430 Full Course Title: Robotics I - I Transcript Title: Robotics I - I Is Consultation with other department(s) required: No Publish in the Following: College Catalog, Time Schedule, Web Page Reason for Submission: Three Year Review / Assessment Report **Change Information:** Consultation with all departments affected by this course is required. **Course description Outcomes/Assessment Objectives/Evaluation** 

**Rationale:** We are updating the master syllabus with newer content so that we can assess it. **Proposed Start Semester:** Fall 2022

**Course Description:** In this hands-on course, students will learn to operate an industrial robot and create entry-level robot programs. The primary emphasis of this course is to introduce students to industrial robotics and automated manufacturing. Student will learn to utilize different jog modes, tool center points and discrete inputs and outputs as well as how these factors affect a robot's motion path. Students with technology interests that enjoy working with their hands like gaming, manipulating code, robotics, and 3D printing are suited for this line of work. This is the first course of the robotics series.

#### **Course Credit Hours**

Variable hours: No Credits: 2 Lecture Hours: Instructor: 15 Student: 15 Lab: Instructor: 30 Student: 30 Clinical: Instructor: 0 Student: 0

Total Contact Hours: Instructor: 45 Student: 45 Repeatable for Credit: NO Grading Methods: Letter Grades Audit Are lectures, labs, or clinicals offered as separate sections?: NO (same sections)

### **<u>College-Level Reading and Writing</u>**

College-level Reading & Writing

## **College-Level Math**

### **Requisites**

## **General Education**

**Degree Attributes** Statewide articulation approved

### **<u>Request Course Transfer</u> Proposed For:**

#### **Student Learning Outcomes**

1. Identify different parts of an industrial robot, classifications of industrial robots and types of automation.

#### Assessment 1

Assessment Tool: Outcome-related module quiz Assessment Date: Winter 2023 Assessment Cycle: Every Three Years Course section(s)/other population: All sections Number students to be assessed: All students How the assessment will be scored: Answer key Standard of success to be used for this assessment: 75% of students will score 75% or higher. Who will score and analyze the data: Departmental faculty

#### Assessment 2

Assessment Tool: Outcome-related questions on the final exam Assessment Date: Winter 2023 Assessment Cycle: Every Three Years Course section(s)/other population: All sections Number students to be assessed: All students How the assessment will be scored: Answer key Standard of success to be used for this assessment: 75% of students will score 75% or higher. Who will score and analyze the data: Departmental faculty

#### 2. Identify and describe end of arm tooling for different robot applications.

#### Assessment 1

Assessment Tool: Outcome-related questions on the final exam

Assessment Date: Winter 2023

Assessment Cycle: Every Three Years

Course section(s)/other population: All sections

Number students to be assessed: All students

How the assessment will be scored: Answer key

Standard of success to be used for this assessment: 75% of students will score 75% or higher. Who will score and analyze the data: Departmental faculty

#### Assessment 2

Assessment Tool: Outcome-related multiple-choice and short answer module quiz questions Assessment Date: Winter 2023

Assessment Cycle: Every Three Years

Course section(s)/other population: All sections

Number students to be assessed: All students

How the assessment will be scored: Answer key

Standard of success to be used for this assessment: 75% of students will score 75% or higher. Who will score and analyze the data: Departmental faculty

3. Recognize and sequence parts of an entry-level robot program.

#### Assessment 1

Assessment Tool: Outcome-related questions on the final exam

Assessment Date: Winter 2023

Assessment Cycle: Every Three Years

Course section(s)/other population: All sections

Number students to be assessed: All students

How the assessment will be scored: Answer key

Standard of success to be used for this assessment: 75% of students will score 75% or higher. Who will score and analyze the data: Departmental faculty

#### Assessment 2

Assessment Tool: Outcome-related multiple-choice and short answer module quiz questions Assessment Date: Winter 2023

Assessment Cycle: Every Three Years

Course section(s)/other population: All sections

Number students to be assessed: All students

How the assessment will be scored: Answer key

Standard of success to be used for this assessment: 75% of students will score 75% or higher. Who will score and analyze the data: Departmental faculty

### **Course Objectives**

- 1. Identify different types of automation.
- 2. Identify parts of an industrial robot.
- 3. Identify classifications of industrial robots.
- 4. Classify industrial robots.
- 5. Create tool center points.
- 6. Utilize different types of tool center points.
- 7. Identify the difference between armloads and payloads.
- 8. Identify different end of arm tooling design considerations.
- 9. Identify how compliance affects the tool center point and the robot program.
- 10. Identify different robot applications and types of tooling.
- 11. Create basic motion routines.
- 12. Identify the different parts of a movement instruction.
- 13. Identify how to utilize different motion types.
- 14. Identify how the motion speed will affect the robot's motion path.
- 15. Identify how the termination type will affect the robot's motion path.
- 16. Identify how the tool center point will affect the robot's motion path.

### **New Resources for Course**

#### **Course Textbooks/Resources**

Textbooks Manuals Periodicals Software

## **Equipment/Facilities**

Level III classroom

<u>Reviewer</u>	<u>Action</u>	<u>Date</u>
Faculty Preparer:		
Sean Martin	Faculty Preparer	Feb 08, 2022
<b>Department Chair/Area Director:</b>		
Allan Coleman	Recommend Approval	Feb 09, 2022
Dean:		
Jimmie Baber	Recommend Approval	Feb 10, 2022

https://www.curricunet.com/washtenaw/reports/course\_outline\_HTML.cfm?courses\_id=11330

<b>Curriculum Committee Chair:</b>		_
Randy Van Wagnen	Recommend Approval	May 31, 2022
Assessment Committee Chair:		
Shawn Deron	Recommend Approval	Jun 13, 2022
Vice President for Instruction:		
Kimberly Hurns	Approve	Jun 14, 2022

## **ROB 101 Robotics I - I** Effective Term: Winter 2017

**Course Cover Division:** Advanced Technologies and Public Service Careers **Department:** Industrial Technology **Discipline:** Robotics **Course Number: 101** Org Number: 14430 Full Course Title: Robotics I - I Transcript Title: Robotics I - I Is Consultation with other department(s) required: No Publish in the Following: College Catalog, Time Schedule, Web Page Reason for Submission: Three Year Review / Assessment Report **Change Information:** Consultation with all departments affected by this course is required. **Course description Outcomes/Assessment** Rationale: Periodic review. Proposed Start Semester: Winter 2017 Course Description: This is the first course of the robotics series. It is a beginning level course where

students are exposed to various aspects of industrial robots and automated manufacturing. Studies include an introduction to hands-on programming using industrial robotics. This course contains material previously taught in ROB 121. ROB 101 is generally offered in the first 7 1/2 week session.

## **Course Credit Hours**

Variable hours: No Credits: 2 Lecture Hours: Instructor: 30 Student: 30 Lab: Instructor: 15 Student: 15 Clinical: Instructor: 0 Student: 0

## Total Contact Hours: Instructor: 45 Student: 45

Repeatable for Credit: NO Grading Methods: Letter Grades Audit Are lectures, labs, or clinicals offered as separate sections?: NO (same sections)

### **College-Level Reading and Writing**

College-level Reading & Writing

## College-Level Math

**Requisites** 

**General Education** 

## **Degree Attributes**

Statewide articulation approved

# Request Course Transfer

**Proposed For:** 

## **Student Learning Outcomes**

1. Identify proper applications for automation.

## Assessment 1

Assessment Tool: departmental exam Assessment Date: Fall 2016 Assessment Cycle: Every Three Years Course section(s)/other population: all sections Number students to be assessed: all students How the assessment will be scored: answer key Standard of success to be used for this assessment: 70% of the students will score 70% or higher. Who will score and analyze the data: Departmental faculty

2. Identify suitable methods of production.

## Assessment 1

Assessment Tool: departmental exam Assessment Date: Fall 2016 Assessment Cycle: Every Three Years Course section(s)/other population: all sections Number students to be assessed: all students How the assessment will be scored: answer key Standard of success to be used for this assessment: 70% of the students will score 70% or higher. Who will score and analyze the data: Departmental faculty

3. Recognize limitations and capabilities of industrial robots.

## Assessment 1

Assessment Tool: departmental exam Assessment Date: Fall 2016

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Assessment Cycle: Every Three Years

Course section(s)/other population: all sections

Number students to be assessed: all students

How the assessment will be scored: answer key

Standard of success to be used for this assessment: 70% of the students will score 70% or higher.

Who will score and analyze the data: Departmental faculty

4. Recognize the key historical events and timeframe in the development of robotics.

Assessment 1

Assessment Tool: departmental exam Assessment Date: Fall 2016 Assessment Cycle: Every Three Years Course section(s)/other population: all sections Number students to be assessed: all students How the assessment will be scored: answer key Standard of success to be used for this assessment: 70% of the students will score 70% or higher. Who will score and analyze the data: Departmental faculty

5. Write entry level robot programs.

## Assessment 1

Assessment Tool: Student written robot program.

Assessment Date: Fall 2016

Assessment Cycle: Every Three Years

Course section(s)/other population: All sections.

Number students to be assessed: All students enrolled.

How the assessment will be scored: Department developed rubric.

Standard of success to be used for this assessment: 70% of the students will score a

3 of 5 or higher on all five areas.

Who will score and analyze the data: Department faculty.

## **Course Objectives**

- 1. Define an industrial robot.
- 2. Name at least three important inventions that led to the development of the robot and include the year of the invention.
- 3. Describe the difference between hard automation and flexible automation.
- 4. Identify rectangular, cylindrical, spherical, articulated and SCARA robots.
- 5. Describe why the popularity of the robot was delayed until 20 years after its first installation.
- 6. Name five applications for industrial robots.
- 7. Describe the difference between open loop and closed loop control systems.
- 8. Describe two major differences between pneumatic and hydraulic systems.
- 9. Identify the capabilities and advantages of industrial robots.
- 10. Recognize the disadvantages of industrial robots.
- 11. Program basic robot actions.

## New Resources for Course

## **Course Textbooks/Resources**

Textbooks Manuals Periodicals Software

Equipment/Facilities Level III classroom

<u>Reviewer</u>	<u>Action</u>	<u>Date</u>
Faculty Preparer:		
Gary Schultz	Faculty Preparer	Apr 20, 2016
<b>Department Chair/Area Director:</b>		
Thomas Penird	Recommend Approval	Apr 28, 2016
Dean:		
Brandon Tucker	Recommend Approval	May 19, 2016
<b>Curriculum Committee Chair:</b>		
David Wooten	Recommend Approval	Sep 19, 2016
Assessment Committee Chair:		
Michelle Garey	Recommend Approval	Sep 22, 2016
Vice President for Instruction:		
Bill Abernethy	Approve	Oct 04, 2016